

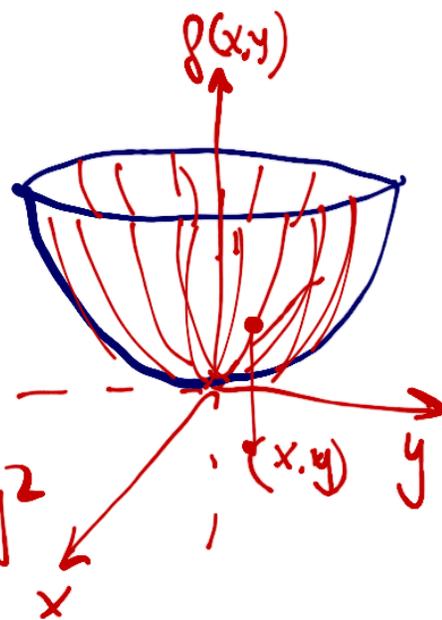
Summary Differentiability in \mathbb{R}^n

A function $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ assigns any arbitrary point in \mathbb{R}^2 to just one value in \mathbb{R}

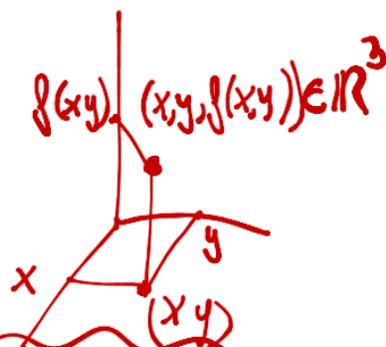
$$(x, y) \rightarrow f(x, y) \in \mathbb{R}$$

Example: $f(x, y) = x^2 + y^2$

$$(x, y) \rightarrow f(x, y) = x^2 + y^2$$



Its graph is a surface !!

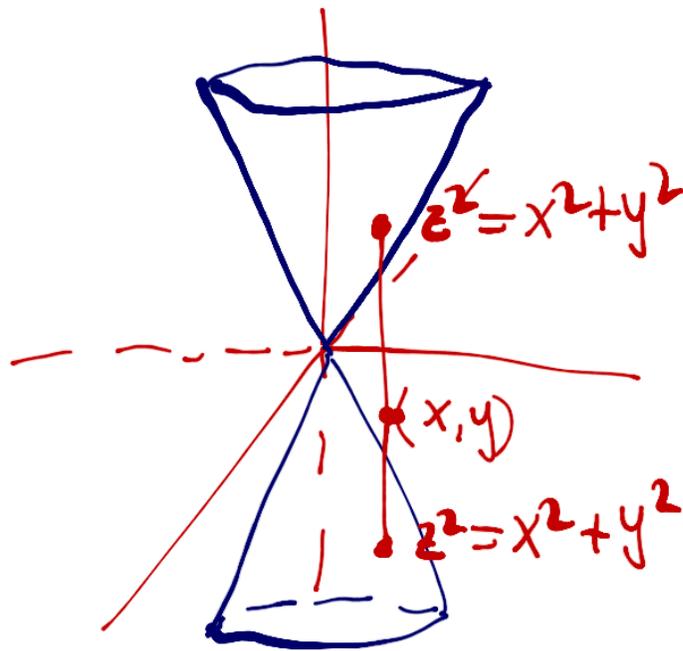


* Such a surface can be written by a formula

$$z = f(x, y)$$

However, that surface might not be a function.

$$z^2 = x^2 + y^2 \quad \text{Cone}$$

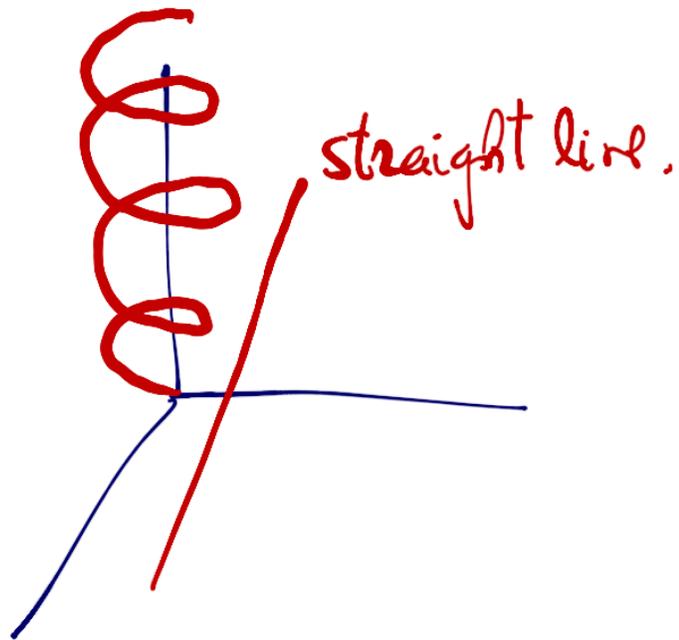


Different functions:

• Scalar functions: $f: \mathbb{R}^n \rightarrow \mathbb{R}$
(magnitudes)

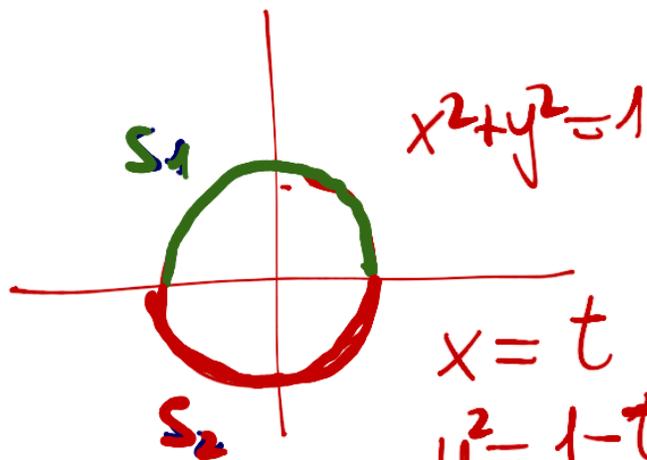
• Vector functions: $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$
(velocity, flux, etc)

• Trajectories $s: \mathbb{R} \rightarrow \mathbb{R}^3$
 $t \rightarrow s(t) = (s_1(t), s_2(t), s_3(t))$



$S(t) \equiv$ parametric expression.

$S(t) \in \mathbb{R}$ given by a parameter t .



$$\left. \begin{array}{l} x = t \\ y^2 = 1 - t^2 \end{array} \right\}$$

$$S_1(t) = (t, \sqrt{1-t^2})$$

$$S_1: \mathbb{R} \rightarrow \mathbb{R}^2$$

$$S_2(t) = (t, -\sqrt{1-t^2})$$

$$S_2: \mathbb{R} \rightarrow \mathbb{R}^2$$

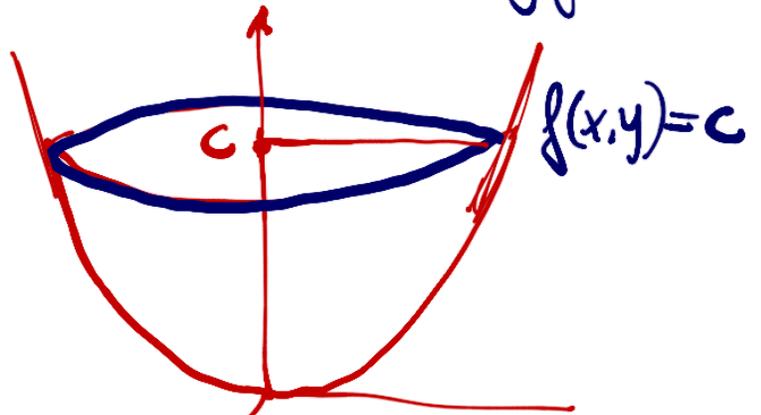
Level curves (or level surfaces)

Curves where the function is constant

$$f(x, y) = c, \quad c \in \mathbb{R}$$

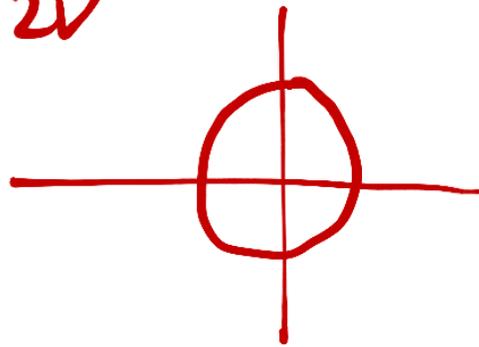
They allow us to draw 3D figures into 2D.

$$f(x, y) = x^2 + y^2$$



Level curve: $x^2 + y^2 = c$ in 2D

Circumferences

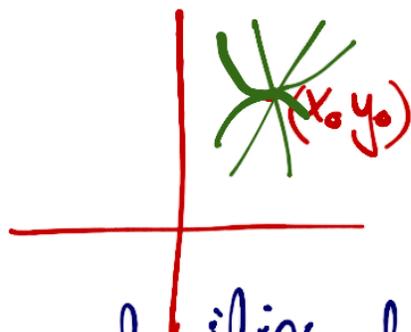


Limits and continuity

If the limit exists it must be unique

This means it CANNOT DEPEND on the trajectory.

In 2D



- Approaching following families of functions $y = kx$ and $y = kx^2$ around the point $(0,0)$ around the point

If we get a value DOES NOT IMPLY that the limit exists

- Polar coordinates. We get a limit if does not depend on θ .

Continuity at x_0 : $\lim_{x \rightarrow x_0} f(x) = f(x_0) \in \mathbb{R}$,
 $x_0 \in \mathbb{R}^n$

Differentiability at x_0 :

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

Derivatives: Partial derivatives.

definition. $\left\{ \begin{array}{l} \frac{\partial f(x_0, y_0)}{\partial x} = \lim_{h \rightarrow 0} \frac{f(x_0, y_0) + h(1, 0) - f(x_0, y_0)}{h} \\ \frac{\partial f(x_0, y_0)}{\partial y} = \lim_{k \rightarrow 0} \frac{f(x_0, y_0) + k(0, 1) - f(x_0, y_0)}{k} \end{array} \right.$

direction (pointing to $(1, 0)$)

direction of y (pointing to $(0, 1)$)

$$f(x_0, y_0) + h(1, 0) = f(x_0 + h, y_0)$$

$$\text{If } (x_0, y_0) = (0, 0), \quad f(h, 0)$$

values for derivations.

ratio of change in the direction of the axis.
(vector of standard basis.)

Directional derivative. $D_{\mathbf{v}} f$

ratio of change in the direction \mathbf{v}

* Existence of derivations { DOES NOT IMPLY diff..
DOES NOT IMPLY cont.

* Differentiability means existence of tangent plane
(smooth function)

Analytically: Existence of partial derivatives

$$0 = \lim_{(x,y) \rightarrow (x_0,y_0)} \frac{\widehat{f(x,y)} - \widehat{f(x_0,y_0)} - \frac{\partial \widehat{f(x_0,y_0)}}{\partial x} (x-x_0) - \frac{\partial \widehat{f(x_0,y_0)}}{\partial y} (y-y_0)}{\|(x,y) - (x_0,y_0)\|}$$

$f: \mathbb{R}^2 \rightarrow \mathbb{R}$.

or

Existence + continuity of partial derivatives

↓
differentiability

$$\lim_{(x,y) \rightarrow (x_0,y_0)} \frac{\| \widehat{F(x,y)} - \widehat{F(x_0,y_0)} - \widehat{JF(x_0,y_0)} \begin{pmatrix} x-x_0 \\ y-y_0 \end{pmatrix} \|}{\|(x,y) - (x_0,y_0)\|} = 0$$

$F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $JF \equiv 2 \times 2$ matrix

In \mathbb{R}^3 , $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

$$\frac{f(x, y, z) - f(x_0, y_0, z_0) - \frac{\partial f}{\partial x}(x-x_0) - \frac{\partial f}{\partial y}(y-y_0) - \frac{\partial f}{\partial z}(z-z_0)}{\|(x, y, z) - (x_0, y_0, z_0)\|}$$

$$Df = \nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

If f is diff. / f a function

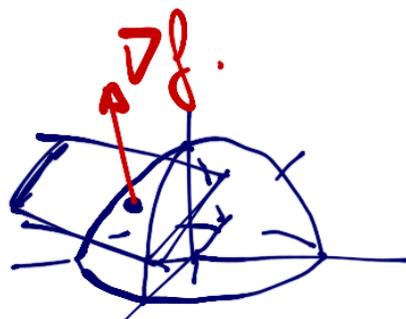
$$D_{\nu}f(x_0) = \left\langle \underbrace{\nabla f(x_0)}_{\text{gradient}}, \nu \right\rangle \quad \text{with } \|\nu\|=1$$

$$\text{Tangent plane: } z = f(x_0, y_0) + \frac{\partial f(x_0, y_0)}{\partial x}(x-x_0) + \frac{\partial f(x_0, y_0)}{\partial y}(y-y_0)$$

- Tangent plane to a surface.

$$f(x, y, z) = 0$$

Implicit form.



gradient vector is orthogonal to the surface

Tangent plane:

$$\nabla f(x_0, y_0, z_0) \cdot \begin{pmatrix} x - x_0 \\ y - y_0 \\ z - z_0 \end{pmatrix} = 0$$

Example: $z^2 = x^2 + y^2$ (cone $\sim f(x, y, z) = x^2 + y^2 - z^2$)

Tangent plane at $(1, 1, 1)$



$$\nabla f(x, y, z) = (2x, 2y, -2z)$$

$$\nabla f(1, 1, 1) = (2, 2, -2) \Rightarrow$$

Tangent plane.

$$(2, 2, -2) \cdot \begin{pmatrix} x - 1 \\ y - 1 \\ z - 1 \end{pmatrix} = 0$$

• $f(x,y) = x^2 + y^2$ function.

Equivalent to $\underbrace{z = x^2 + y^2}_{\text{Formula}} \equiv \text{surface.}$

$$g(x,y,z) = x^2 + y^2 - z.$$

$$\nabla g(x,y,z) = (2x, 2y, -1)$$

At $(1, 1, 2)$ on the surface.

$$f(1,1) = 2 \quad \nabla f = (2x, 2y) \Rightarrow \nabla f(1,1) = (2, 2)$$

$$\text{option a): } z = f(1,1) + \nabla f(1,1) \begin{pmatrix} x-1 \\ y-1 \end{pmatrix}$$

$$z = 2 + 2(x-1) + 2(y-1)$$

$$2(x-1) + 2(y-1) - (z-2) = 0$$

$$\text{option b): } \nabla g(1,1,2) \begin{pmatrix} x-1 \\ y-1 \\ z-2 \end{pmatrix} = (2, 2, -1) \begin{pmatrix} x-1 \\ y-1 \\ z-2 \end{pmatrix} = 0$$

Chain rule:

$$D(g \circ f)(x_0) = Dg(f(x_0)) \cdot Df(x_0)$$

matrices.

• In 1D $y = f(x)$ and $x = x(t)$

then $y = f(x(t)) = h(t)$

$$\text{So } \frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt} = \frac{d f(x(t))}{dx} \cdot \frac{dx}{dt}$$
$$\frac{d f(x(t))}{dt}$$

$$\text{In } 2D \quad \underline{z = f(x, y)}, \quad x \equiv x(t) \\ y \equiv y(t)$$

$$f: \underline{\mathbb{R}^2} \rightarrow \mathbb{R}. \quad Df = \nabla f$$

$$z = f(x(t), y(t)) = f(s(t))$$

$$s(t) = (x(t), y(t))$$

$$s: \mathbb{R} \rightarrow \mathbb{R}^2$$

Thanks to the chain rule

$$\frac{dz}{dt} = \frac{df(s(t))}{ds} \cdot \frac{ds}{dt} = \nabla f(s(t)) \cdot \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \end{pmatrix}}_{\nabla f} \cdot \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

Example:

$$z = x^2 y + 3xy^4$$

$$\begin{cases} x = \sin 2t \\ y = \cos t \end{cases} \quad \text{Find } \frac{dz}{dt}$$

$$z = x^2(t) y(t) + 3x(t) y^4(t)$$

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

$$= \underbrace{(2xy + 3y^4)}_{\frac{\partial z}{\partial x}} \underbrace{2\cos 2t}_{\frac{dx}{dt}} - \underbrace{(x^2 + 12xy^3)}_{\frac{\partial z}{\partial y}} \underbrace{\sin t}_{\frac{dy}{dt}}$$

$$\frac{dz}{dt} = 2x(t) \frac{dx}{dt} y(t) + x^2(t) \frac{dy}{dt}$$

$$+ 3y^4(t) \frac{dx}{dt} + 12x(t) y^3(t) \frac{dy}{dt}$$

Problem 10 in 1.3

$$\text{ii) } s'(t) = F(s(t))$$

$$s(t) = \left(e^{2t}, \frac{1}{t}, \log t \right), \quad \underline{F(x, y, z)} = \underline{(2x, -y^2, y)}$$



$$s'(t) = \frac{ds(t)}{dt} = \left(2e^{2t}, -\frac{1}{t^2}, \frac{1}{t} \right)$$

$$F(s(t)) = F\left(\underline{e^{2t}}, \underline{\frac{1}{t}}, \underline{\log t} \right) =$$

$$= \left(2e^{2t}, -\frac{1}{t^2}, \frac{1}{t} \right)$$

- The pressure P (in kilopascals) volume V (litres) and temperature T (in kelvins) of a mole of an ideal gas are related by the equation

$$PV = 8.31 T$$

Find the rate at which pressure is changing when $T = 300 \text{ K}$ and increasing at a rate of 0.1 K/s and $V = 100 \text{ L}$ and increasing at a rate of 0.2 L/s

$$P = \frac{8.31 T}{V} = P(T, V) \equiv P(T(t), V(t))$$

$$T = 300 \text{ K} \quad \frac{dT}{dt} = 0.1, \quad V = 100 \quad \frac{dV}{dt} = 0.2$$

rate of change for $P \equiv \frac{dP}{dt}$, $P = \frac{8'31 T}{V}$

$$\frac{dP}{dt} = \frac{\partial P}{\partial T} \underbrace{\frac{dT}{dt}}_{0'1} + \frac{\partial P}{\partial V} \underbrace{\frac{dV}{dt}}_{0'2}$$
$$= \frac{8'31}{V} \cdot 0'1 - \frac{8'31 T}{V^2} \cdot 0'2$$

$$= \frac{8'31}{100} \cdot 0'1 - \frac{8'31 \cdot 300}{(100)^2} \cdot 0'2 = \underline{-0'04155}$$

The pressure decreases at that rate.

Implicit differentiation

Write a function

<u>Implicit form</u>	<u>Explicit form</u>	Derivative
$xy=1$	$y=\frac{1}{x}$	$\Rightarrow \frac{dy}{dx} = -\frac{1}{x^2}$

However we cannot use those two forms when we are unable to solve the equation for y as a function of x

$$x^2 - 2y^3 + 4y = 2$$

To differentiate we must use
Implicit differentiation (chain rule)

- Every term depending on x we differentiate as usual
- Every term involving $y \equiv y(x)$ we must apply the chain rule.

Example: $x^2 + y^2 = 1$, $y \equiv y(x)$

$$\frac{d}{dx} [x^2 + y^2] = \frac{d}{dx} [1] = 0$$

$$2x + 2y \frac{dy}{dx} = 0 \Rightarrow \frac{dy(x)}{dx} = \frac{-x}{y}$$

In several variables.

$$F(x, y) = 0 \quad \text{or} \quad F(x, y(x)) = 0$$

Applying the chain rule. $\frac{dF}{dx} = \frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0$

1

$$\frac{dy}{dx} = - \frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial y}}$$

Ex: $x^3 + y^3 = 3xy \Rightarrow F(x,y) = x^3 + y^3 - 3xy$

$$\frac{dy}{dx} = - \frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial y}} = - \frac{3x^2 - 3y}{3y^2 - 3x} = - \frac{x^2 - y}{y^2 - x}$$

explicit form

If $\boxed{z = f(x,y)}$ in implicit form

$$F(x, y, f(x,y)) = 0 \quad \left| \begin{array}{l} f: \mathbb{R}^2 \rightarrow \mathbb{R} \\ (x,y) \text{ indep.} \\ \text{variables.} \end{array} \right.$$

Using the chain rule.

$$\frac{\partial F}{\partial x} \cdot \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} + \frac{\partial F}{\partial z} \frac{\partial z}{\partial x} = 0$$

1
0

Infectious disease outbreak size.

Mathematical models predict the fraction of population that will be infected when a disease begins to spread.

$$\underbrace{\rho e^{-q\Delta} - 1 + \Delta = 0}_{F(\rho, q, \Delta)}$$

$$\rho e^{-q\Delta} = 1 - \Delta$$

Kermack-McKendrick model

$\Delta \equiv$ fraction of population infected.

$\rho \equiv$ initially population susceptible to infection

$q \equiv$ measure of transmissibility

How does the outbreak size Δ change with
an increase in q ? $F(\rho, q, \Delta) = \rho e^{-q\Delta} - 1 + \Delta$

$$\frac{\partial \Delta}{\partial q} = - \frac{\frac{\partial F}{\partial q}}{\frac{\partial F}{\partial \Delta}} = \frac{\square}{\square}$$

$$F(\ell, q, \Delta(q)) = 0$$

$$\frac{\partial F}{\partial \ell} \cdot \frac{d\ell}{dq} + \frac{\partial F}{\partial q} \frac{dq}{dq} + \frac{\partial F}{\partial \Delta} \frac{\partial \Delta(q)}{\partial q} = 0$$

//
//
//

$$\frac{\partial \Delta}{\partial q} = - \frac{\frac{\partial F}{\partial q}}{\frac{\partial F}{\partial \Delta}}$$

$$F(\ell, q, \Delta(q)) = \ell e^{-q/\Delta(q)} - 1 + \Delta(q) = 0$$